Theory of Ship Waves (Wave-Body Interaction Theory)

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1) In deriving Euler's equation, the shear force due to the viscosity was not considered in the text, and thus the force acting on the fluid volume in the *i*-th direction was described as $-p n_i$. When the viscous shear is present, the corresponding force can be written as

$$\tau_{ij} n_j = \left\{ -p \,\delta_{ij} + \mu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \right\} n_j \tag{1}$$

where δ_{ij} is the Kronecker delta function, equal to 1 if i = j and 0 if $i \neq j$, and μ is the coefficient of viscosity. Then by following the same procedure as in deriving (1.14) in the text, derive the Navier-Stokes equation. The final result will be:

$$\frac{\partial u_i}{\partial t} + u_j \frac{\partial u_i}{\partial x_j} = -\frac{1}{\rho} \frac{\partial p}{\partial x_i} + \frac{\mu}{\rho} \frac{\partial^2 u_i}{\partial x_i^2} + g \,\delta_{i3} \tag{2}$$

2) Page 4 in the text says the normal vector can be obtained by the formula $\mathbf{n} = \nabla F / |\nabla F|$, provided that the body surface is represented by F(x, y, z) = 0. Confirm this relation for a (2-dimensional) ellipse and a (3-dimensional) prolate spheroid given by:

$$\left. \begin{array}{l} x = a \cos \theta \\ y = a\epsilon \sin \theta \cos \varphi \\ z = a\epsilon \sin \theta \sin \varphi , \quad \epsilon = b/a \end{array} \right\}$$
(3)

The result for a prolate spheroid will be given as follows:

$$n_1 = \epsilon \cos \theta / \Delta, \ n_2 = \sin \theta \cos \varphi / \Delta, \ n_3 = \sin \theta \sin \varphi / \Delta.$$

where

$$\Delta = \sqrt{\sin^2 \theta + \epsilon^2 \cos^2 \theta}$$
, $\epsilon = b/a$.